

## Lecture 0: Preliminary

### 0.1 STAT4351 Review

- sample space, probability of events, Kolmogorov's axioms, independence and dependence, Bayesian methods
- discrete vs. continuous random variables
- PMF and PDF of univariate and multivariate random variables
- expectation, variance, mgf, covariance, etc.
- special probability distributions
- functions of random variables, transformations for one and several variables
- law of large numbers, central limit theorem, sampling distributions

### 0.2 Mathematical Foundations

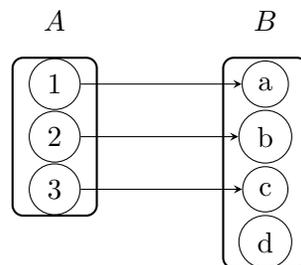
**Definition 0.1** A function is **injective** (one-to-one) if different elements in  $A$  are mapped to different elements in  $B$ . Formally,

$$\forall x_1, x_2 \in A, \quad f(x_1) = f(x_2) \implies x_1 = x_2 \quad [\text{or}] \quad \forall x_1, x_2 \in A, \quad x_1 \neq x_2 \implies f(x_1) \neq f(x_2)$$

**Definition 0.2** A function is **surjective** (onto) if every element in  $B$  has at least one preimage in  $A$ . Formally,

$$\forall y \in B, \quad \exists x \in A \text{ such that } f(x) = y$$

**Example 0.1** A function  $f : A \rightarrow B$  that is injective, but not surjective:



**Example 0.2** The function  $g : \mathbb{R} \rightarrow \mathbb{R}, g(x) = x^2$  is not injective and not surjective.

*Proof.* Counter example for injective:  $g(1) = g(-1) = 1$ . Counter example for surjective:  $g(x) \geq 0$  for all  $x \in \mathbb{R}$ .  $\square$

**Definition 0.3** A function is **bijective** (one-to-one correspondence) if it is both injective and surjective. Formally,

$$\forall y \in B, \quad \exists! x \in A \text{ such that } f(x) = y \quad (! \text{ means "unique"})$$

Alternatively,  $f : A \rightarrow B$  is **bijective** if and only if  $\exists g : B \rightarrow A$  (inverse of  $f$ ) such that  $g(f(x)) = x$ ,  $\forall x \in A$ , and  $f(g(y)) = y$ ,  $\forall y \in B$ .

**Example 0.3** Consider the function  $f : \mathbb{R} \rightarrow \mathbb{R}$  given by  $f(x) = 2x + 3$ .

(a) Injective?

*Proof.* Suppose  $f(x_1) = f(x_2)$ , then  $2x_1 + 3 = 2x_2 + 3 \implies x_1 = x_2$  so  $f$  is injective.  $\square$

(b) Surjective?

*Proof.* For any  $y \in \mathbb{R}$ , solving  $y = 2x + 3$  for  $x$  gives  $x = \frac{y-3}{2}$ . Since a solution for  $x$  exists  $\forall y \in \mathbb{R}$ ,  $f$  is surjective.  $\square$

(c) Bijective?

*Proof.* Since  $f$  is both injective and surjective, it is bijective.  $\square$

### 0.3 Moment Generating Function (mgf)

As the name suggests, mgfs are used to find the “moments” of a distribution.

**Definition 0.4** If  $\mathbb{E}(|X^k|) < +\infty$ , we define the following quantity

$$\mathbb{E}(X^k) = \begin{cases} \sum_x x^k f(x), & X \text{ is discrete random variable,} \\ \int_{-\infty}^{\infty} x^k f(x) dx, & X \text{ is continuous random variable.} \end{cases}$$

as the  $k^{\text{th}}$  **moment of a random variable  $X$**  ( $k = 1, 2, \dots$ ), denoted  $m_k(X)$  or  $m_k$ .

**Definition 0.5** The **moment generating function** of  $X$  is defined as

$$M_X(t) = \text{mgf}_X(t) = \mathbb{E}(e^{tX})$$

if the expectation exists for  $-h < t < h$ , for some constant  $h > 0$ .

**Remark 0.1** The Taylor Series expansion of  $e^{tX}$  is given by

$$e^{tX} = 1 + tX + \frac{(tX)^2}{2!} + \cdots + \frac{(tX)^k}{k!} + \cdots$$

Then, taking the expectation we know

$$\begin{aligned} \mathbb{E}(e^{tX}) = M_X(t) &= 1 + t\mathbb{E}(X) + \frac{t^2}{2!}\mathbb{E}(X^2) + \cdots + \frac{t^k}{k!}\mathbb{E}(X^k) + \cdots \\ &= 1 + tm_1 + \frac{t^2}{2!}m_2 + \cdots + \frac{t^k}{k!}m_k + \cdots \end{aligned}$$

where  $m_k$  denotes the  $k^{\text{th}}$  moment, and can be obtained by differentiating the mgf  $k$ -times and setting  $t = 0$ .

**Remark 0.2** Properties of mgfs:

1. (Distribution determination) If two random variables  $X, Y$  has the same mgf for all  $-h < t < h$ , for some constant  $h > 0$ , then  $X$  and  $Y$  follow the same distribution (i.e.,  $X \stackrel{d}{=} Y$ ).
2. (Independence) Two random variables  $X, Y$  are independent if and only if

$$\text{mgf}_{X,Y}(t, s) = \mathbb{E}(e^{tX+sY}) = \text{mgf}_X(t)\text{mgf}_Y(s).$$

## 0.4 Cumulant generating function (CGF)

If the moment generating function  $M(t)$  of the random variable  $X$  exists, taking the logarithm of the mgf is known as the cumulant generating function (CGF) of the random variable  $X$ .

$$C(t) = \log M(t) = \log E(e^{tX}), \quad -h < t < h (\exists h > 0)$$

It is often denoted by  $\text{cgf}$ . The Taylor expansion of the cumulant generating function is

$$C(t) = \sum_{r=0}^{\infty} \frac{C^{(r)}(0)}{r!} t^r, \quad -h < t < h (\exists h > 0), \quad r = 1, 2, \dots$$

where  $C(0) = 0$ , and the coefficients  $C^{(r)}(0)$  are called the  $r$ -th cumulants of  $X$ , denoted by  $c_r(X)$  or simply  $c_r$ . That is,

$$C(t) = \sum_{r=1}^{\infty} \frac{c_r(X)}{r!} t^r, \quad -h < t < h (\exists h > 0).$$

The relationship between the cumulants  $c_r$  and the moments  $m_k$  can be derived from

$$\log \left( 1 + \sum_{k=1}^{\infty} \frac{m_k t^k}{k!} \right) = \sum_{r=1}^{\infty} \frac{c_r}{r!} t^r, \quad -h < t < h (\exists h > 0)$$

Using the expansion for  $\log(1 + A)$  as follows

$$\log(1 + A) = A - \frac{A^2}{2} + \frac{A^3}{3} - \dots, \quad (-1 < A < 1),$$

where  $A = m_1 t + m_2 t^2/2! + m_3 t^3/3! + \dots$ , and expanding in powers of  $t$ , we get:

$$c_1 = m_1, \quad c_2 = 2! (m_2/2! - (m_1)^2/2!) = m_2 - (m_1)^2, \dots$$

Thus, the cumulants  $c_1$  and  $c_2$  represent the mean and variance, respectively.

There are some interesting properties for the standardized random variable  $Z = \frac{X - \mu}{\sigma}$ .

- The relationship between the moments  $m_r(Z)$  and cumulants  $c_r(Z)$  is given by

$$c_3(Z) = m_3(Z) = \mathbb{E} \left[ \left( \frac{X - \mu}{\sigma} \right)^3 \right]$$

$$c_4(Z) = m_4(Z) - 3 = \mathbb{E} \left[ \left( \frac{X - \mu}{\sigma} \right)^4 \right] - 3,$$

where  $c_3(Z)$  is the third cumulant, and  $c_4(Z)$  is the fourth cumulant, which define the skewness and kurtosis of  $X$ , respectively.

- The relationship between the cumulant generating functions of  $Z$  and  $X$ , and between the cumulants of  $Z$  and  $X$ , is given by:

$$c_r \left( \frac{X - \mu}{\sigma} \right) = \frac{c_r(X)}{\sigma^r}, \quad r = 3, 4, \dots$$

*Proof.* [Sketch of Proof] The skewness and kurtosis are defined through the standardization of  $X$ .

$$M_Z(t) := 1 + \sum_{k=1}^{\infty} \frac{m_k t^k}{k!}, \quad A := \sum_{k=1}^{\infty} \frac{m_k t^k}{k!}$$

Then:

$$\mathbb{E}[Z] = m_1 = 0, \quad \text{Var}(Z) = 1, \quad m_2 - m_1^2 = m_2,$$

and therefore,

$$A = \frac{1}{2} t^2 + \frac{m_3}{3!} t^3 + \frac{m_4}{4!} t^4 + \dots$$

Now, the cumulant generating function (CGF) of  $Z$ , denoted by:

$$\text{cgf}_Z(t) := \sum_{r=1}^{\infty} \frac{c_r t^r}{r!}$$

can be derived by comparing the coefficients as follows

$$\text{cgf}_Z(t) = \log M_Z(t) = \log(1 + A) = A - \frac{A^2}{2} + \frac{A^3}{3} - \dots$$

and we can conclude that

$$c_3 = 3! \cdot \frac{m_3}{3!} = m_3, \quad c_4 = 4! \left( \frac{m_4}{4!} - \frac{1}{2} \cdot \frac{1}{(2!)^2} \right) = m_4 - 3.$$

For the second bullet point, from the definition of the mgf, we have

$$M_Z(t) = E \left[ e^{t \frac{X-\mu}{\sigma}} \right] = E \left[ e^{-\frac{\mu t}{\sigma}} e^{\frac{t}{\sigma} X} \right] = e^{-\frac{\mu t}{\sigma}} M_X \left( \frac{t}{\sigma} \right)$$

Now, taking the logarithm of both sides

$$\text{cgf}_Z(t) = \log M_Z(t) = -\frac{\mu t}{\sigma} + \log M_X \left( \frac{t}{\sigma} \right) = -\frac{\mu t}{\sigma} + \text{cgf}_X \left( \frac{t}{\sigma} \right)$$

From this, we get

$$c_r(Z) = \text{cgf}_Z^{(r)}(0) = \frac{1}{\sigma^r} \cdot \text{cgf}_X^{(r)}(0) = \frac{1}{\sigma^r} \cdot c_r(X), \quad r = 3, 4, \dots$$

□